CS 6420 Operating Systems

Summer Quarter, 1999

Midterm

Friday July 16, 1998

Reminder: OPEN Book and OPEN Notes

1. Anderson's Array Based Queueing Lock (20 points)

Anderson's array based queueing lock is shown below, with Mellor-Crummey's correction, and Riley's correction to Mellor-Crummey's correction. This version assumes *numprocs* is 4, meaning we have exactly four CPU's which can be contending for the lock. The pseudo-code is given in a C-like format, rather than the Pascal-like format in the paper. Pay careful attention to the initialization of the fields in the Lock structure, which is slightly different than that given in the paper. *Think carefully about parts a and b*.

- (a) As coded below, what is the smallest and largest (ie. the range of values) that will ever be assigned to variable *Lock.nextslot*?
- (b) As coded below, and remembering that each processor has a private copy of variable *myplace*, what is the smallest and largest (ie. the range of values) that any instance of variable *myplace* can be assigned?
- (c) Variable Lock.slots is shown to be initialized to [T, F, F, F]. During normal execution of the algorithm, is it possible that Lock.slots will have the value [F, F, F, F]? If so, explain what this means, or if not explain why not.
- (d) Is it possible for variable *Lock.slots* to have the value [T, T, T, T]? Is so, explain what this means, or if not explain why not.

```
#define F 0
#define T 1
#define numprocs 4
typedef struct {
  int slots[numprocs] = {T, F, F};
  int nextslot = numprocs;
} Lock;
void acquire_lock( Lock* L, int* myplace);
Ł
  *myplace = fetch_and_increment(&L->nextslot);
  if ((*myplace % numprocs) == 0) /* % is the mod operator */
    atomic_add(&L->nextslot, -numprocs);
  *myplace = *myplace % numprocs;
  while(L->slots[*myplace] == F) spin;
  L->slots[*myplace] = F;
}
void release_lock(Lock* L, int* myplace)
L->slots[(*myplace + 1) % numprocs] = T;
}
```

2. Barriers (20 points)

The code for *BuggyBarrier2* that we discussed in class, along with the *Sense Reversing Centralized Barrier* (Mellor-Crummey algorithm 7, slightly modified) is shown below.

- (a) What is the problem with BuggyBarrier2? Explain in detail why it cannot work.
- (b) The Sense Reversing barrier is quite similar to *BuggyBarrier2*, but it is in fact correct. Explain how the Sense Reversing barrier corrects the problem with *BuggyBarrier2*.
- (c) Notice that the Sense Reversing barrier shown below has added a processor private variable Barrier Invocation Number (BIN), which simply counts by one each time the Central_Barrier routine is entered. Is it possible for some processor to be executing in routine Central_Barrier with BIN = k ($k \ge 2$) at the same time as some other processor in also executing in routine Central_Barrier with BIN = k ($k \ge 2$) at the same time as some other processor in also executing in routine Central_Barrier with BIN = (k 1)? If so explain how this can happen, or explain why not.
- (d) Is it possible for some processor to be executing in routine Central_Barrier with BIN = k $(k \ge 2)$ at the same time as some other processor in also executing in routine Central_Barrier with BIN = (k 2)? If so explain how this can happen, or explain why not.

Algorithm BuggyBarrier2, by George Riley

```
1 shared int CountBarrier = 0;
```

- 2 **Procedure** BuggyBarrier2
- 3 $mycount = \mathbf{FetchAndIncrement}(CountBarrier);$
- 4 $\mathbf{if}(mycount == (numprocs 1))$ {
- 5 CountBarrier = 0; // All there, let others know and reset
- 6 else
- 7 **while**(*CountBarrier* != 0) *spin* // Wait for others

Sense-Reversing Centralized Barrier

- 1 shared int CountBarrier = P;
- 2 shared Boolean sense = TRUE;
- 3 processor private Boolean $local_sense = TRUE;$
- 4 processor private int BIN = 0;
- 5 **Procedure** Central_Barrier
- $6 \qquad BIN = BIN + 1;$
- 7 $local_sense = NOT$ $local_sense;$
- 8 $mycount = \mathbf{FetchAndDecrement}(CountBarrier);$
- 9 $\mathbf{if}(mycount == 1)$ {
- 10 CountBarrier = P; // All there, reset count for next pass
- 11 $sense = local_sense; // All there, let others know$
- 12 else
- 13 $\mathbf{while}(Sense \mathrel{!= local_sense}) spin // Wait for others$

- 3. Filaments (20 points) For this question, assume we are running on a platform with 4 CPU's, and we are creating 4 servers in our filaments code (ie. we are calling f_initialize(4).
 - (a) The code for sequential_code on page 5 is reproduced below. Notice that on line 3 the variable k is incremented, but not atomically. Keeping in mind that we have defined 4 servers, it this an error? Should we have used an atomic increment here? Explain why or why not.
 - (b) Referring to the main program at the bottom on page 5, give pseudo code or a verbal explanation of what the subroutine f_iterative_thread has to do to work properly.

```
sequential_code()
1
2
     real** temp;
З
     k++
4
     if (k > MAXITERS or maxdiff < EPSILON) then return DONE
     temp = old; old = new; new = temp;
5
6
     maxdiff = 0.0
7
     return NOTDONE
8
   end
```

4. Remote Procedure Calls (20 points)

- (a) Why is it necessary for the RPC Server to buffer the *Reply* blocks for possible later reuse?
- (b) Of the RPC server application, RPC server stub, or RPC server runtime (see fig. 1 in the RPC paper), which of these does the buffering of the Replies?
- (c) When can these buffered reply blocks be discarded?
- (d) What is the purpose of the random value Y in the RFA message shown in fig 2 of the Secure RPC paper?
- (e) Assume that an RPC client is system A and the RPC server is system B. The protocol for the *Request for Authenticator RFA* message between B and A is somewhat complex. It would seem simpler just to have B ask the KDC for the conversation key (which would of course be given encrypted with B's private key). Give two reasons why Birrell did not design it this way.
- 5. Active Messages (20 points)
 - (a) Give two reasons why an implementation of RPC's using active messages can perform so much better than traditional RPC's.
 - (b) Explain two problems with the original design of active messages that the *Optimistic* active messages design is attempting to solve. How does it solve them?
 - (c) Why does the performance of *Optimistic* active messages drop off so dramtically as the number of processes increases above a certain threshold (see figure 2 in the Wallach paper).